

# ANTARES 700XA



X-RAY REFERENCE DRILLING MACHINE  
WITH AUTOMATED LOAD/UNLOAD SYSTEM



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“Antares 700 XA is designed to drill optimized reference holes on multi-layer panels. The automatic loader/unloader allows the machine to operate in full autonomy after the batch of panels is initialized”

**HARDWARE**

- Latest generation CNC
- Position transducers with  $1\mu$  resolution
- Linear motors
- High reliability X-Ray system
- High sensitivity X-Ray camera
- Compact solution (see overall dimensions)

**SOFTWARE**

- User friendly interface
- All data of measured panels stored into a \*.mdb file (network access)
- Measuring functions available

5004 - Running Step 1 - Measure Pads

Loaded Program : Inner Cedal 4 pt 2mm.prg

Measures

Target Parameters		Measurements Results						
Id	X	Y	$\emptyset$	K	Xm	Ym	$\emptyset$	%
1	-253.000	198.000	2.000	2	-252.911	198.000	1.840	-8
2	253.000	198.000	2.000	2	252.911	198.000	1.966	-2
3	253.000	-198.000	2.000	2	252.819	-197.973	1.971	-1
4	-253.000	-198.000	2.000	2	-252.913	-197.436	1.869	-7

Drills

Holes Parameters		Real Hole Position			
Id	Drill Type	X	Y	Real X	Real Y
1	Drill Position	-248.000	-90.000	0.000	0.000
2	Drill Position	-248.000	90.000	0.000	0.000
3	Drill Position	248.000	90.000	0.000	0.000
4	Drill Position	248.000	-90.000	0.000	0.000

Calculated Values

	Measured Distances	Abs. Deform.	% Deform.
Offset X : -2.748	Upper X 505.822	-0.178	X -0.044
Offset Y : 2.240	Lower X 505.732	-0.268	
Angle : -0.066	Right Y 395.973	-0.027	Y -0.075
	Left Y 395.436	-0.564	

Operating

- Main Page
- Manual
- Process Status

Configuration

- Settings
- Calibration

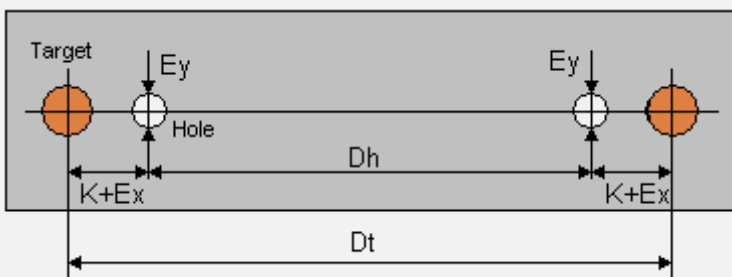
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**TARGET**

- Fully programmable target recognition
- Blob analysis and pattern matching technologies
- Easy management of layers

**HOLES**

- Optimised drilling (best fit)
- On-target drilling
- Scaled drilling



**Definition of optimised drilling accuracy:**

$D_t$  = Measured distance between targets

$D_h$  = Distance between holes

$$2K = D_t - D_h$$

$E_x$  = Errors along X axis (scale error)

$E_y$  = Errors along Y axis

# TWO SPINDLE VERSIONS

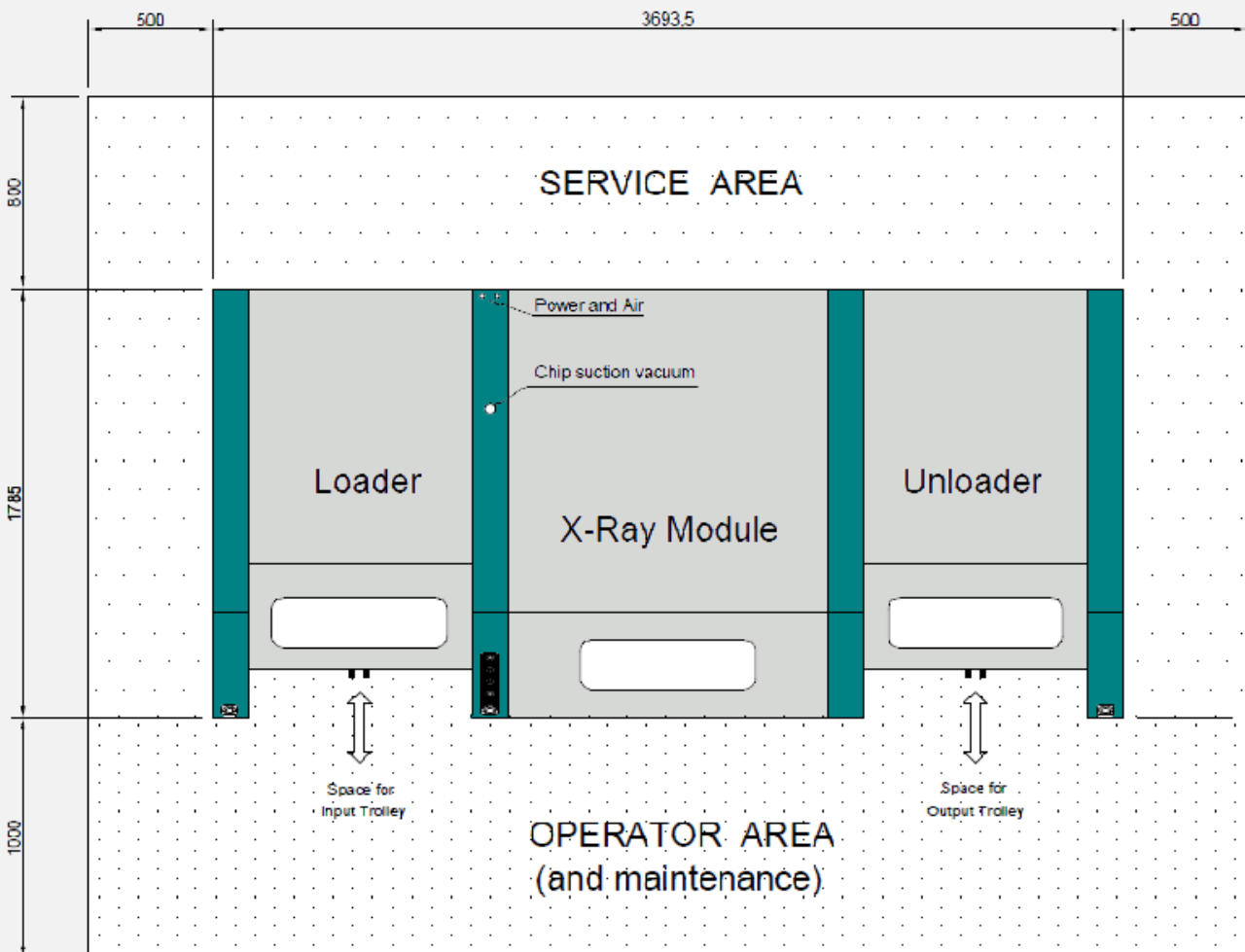
## PNEUMATIC

- 30.000 rpm fixed speed
- Adjustable descending speed
- Single tool
- 16  $\mu\text{m}$  run-out
- Easy and fast tool change

## ELECTRIC

- Max 60.000 rpm
- Position and speed controlled Z axis
- ATC (automatic tool change)
- 4 station tool magazine
- TLD (tool length device)
- Within 2  $\mu\text{m}$  run-out

# INSTALLATION REQUIREMENTS



## VACUUM CHIP SUCTION

- De-pressure: 150 mbar
- Flow: 14 L/min (0,84 m<sup>3</sup>/h)
- Connection size: 40 mm

## ENVIRONMENT

- Room temp: 20 – 23 °C
- Relative humidity: < 55%
- Floor: Absence of vibrations
- Machine weight: 4000 Kg

## MACHINE HEIGHT

- Top: 1500 mm from the floor
- With front door open ad totem lights: approx. 2100 mm

# SPECIFICATIONS

<b>Process Specifications</b>	Measuring Accuracy	±15 µm	Within a vision area of 640x480 mm (25"x 19")
	Drill-on-target accuracy	±15 µm	Round target
	Optimised drilling accuracy	±18 µm (See description)	Round targets @ Dt = 600 mm and Dh=Dt - 5 mm
	Cycle time	20 s	4 targets + 3 holes
	Productivity	3 panels / minute	4 targets + 3 holes

<b>Machine Specifications</b>	Electrical supply	3 Ph + Ground – 50/60 Hz	Voltage on request
	Electrical power consumption	2 KVA (Max)	
	Air pressure supply	6 ÷ 10 Bar	
	Air consumption	400 L/min (Avg)	1400 L/min (Peak)
	N. of position controlled axes	3	4 with electro-spindle
	Max axes speed	60 m/min	
	Position accuracy	± 3 µm	
	Position transducer resolution	± 1 µm	Heidenhain
	X / Y strokes	800 / 900 mm	
	Vision Area	700 x 580 mm	Blind area 150 x 250 mm at the centre
	Z-axis motion system	Pneumatic	
	Z axis stroke	40 mm	
	Z drilling feed	0,2 ÷ 2 m/min	Adjustable
	Spindle type	Turbine	
	Spindle speed	30.000 rpm	Fixed
	Tool change	Manual	
	Tool diameters	1 ÷ 5 mm	
	Z-axis motion system	Position Controlled	
	Z axis stroke	50 mm	
	Z drilling feed	0,2 ÷ 2 m/min	Adjustable
	Spindle type	Turbine	
	Spindle speed	Up to 60.000 rpm	Programmable for each tools
	Tool change	Automatic	4 tools
	Tool diameters	1 ÷ 5 mm	
	Chips evacuation system	Centralized	(on board as option)
	Panel clamp system	Vacuum - Venturi	Table centre (Blind area 150x250 mm)
	Panel load mode	Automatic	From left cart
Panel unload mode	Automatic	To right cart	
Rejection of bad panels	Automatic	To right cart with an offset	
Panel reference system	n. 2 Cross laser lines	For manual load mode	
X-Ray source	50 KV – 1mA	Focal spot = 50 µm	
Radiation leakage	< 1 µSv / hour	Euratom certificate	
X-Ray sensor type	CCD + Scintillator		
Sensor field of view	20 x 15 mm		
Vision system accuracy	± 4 µ		

<b>Panel Specs Automated Load/Unload</b>	Max. dimensions	580(X) x 660(Y) mm	20" x 26"
	Min. dimensions	320(X) x 320(Y) mm	12" x 18"
	Max. Weight	3,0 Kg	6.6 Lb per panel
	Thickness	0,3 to 4 mm	Indicative
	Min. Thickness	Down to 0,1 mm	With special vacuum table

<b>Panel Specifications Manual Mode</b>	Max. dimensions	700(X) x 700(Y) mm	27.5" x 27.5"
	Min. dimensions	300(X) x 200(Y) mm	12" x 8"
	Thickness	0,3 to 10 mm	0.012" to 0.40" (Indicative)
	Min. thickness	Down to 0,100 mm	0.004" (With special vacuum seal)